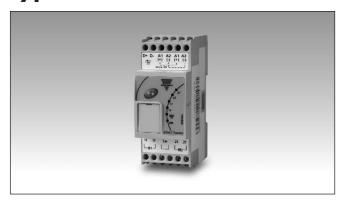
# Smart Dupline® Control for AC Rollerblind Motor Type SH2ROAC224





- Up/down control for two AC rollerblind motors
- DC power supply
- Relay load 5A
- 2 DIN housing
- LED indication for power supply, Dupline® bus, motor up, motor down
- Connection to other cabinet modules via local bus

### **Product Description**

This is a 2-DIN relay output module to control AC rollerblind motors.

It has been developed to be connected to and controlled by the smart-house system controllers.

The rollerblind motor is driven by two relays in series:

one to switch the motor ON/OFF and the second one to control the direction UP/DOWN. These two relays are controlled in such a way to respect the motor timing before any reversing of the motor direction.

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### **Type Selection**

Housing	Mounting	Relay load	Relay output	Supply: 15 to 30 VDC
2 DIN	DIN-rail	5A	2 SPST + 2 SPDT relay	SH2ROAC224

## **Output Specifications**

Relay output		2 SPST (R1, R2) + 2 SPDT (R3-R4) relay	
Resistive load AC1		5 A/240 VAC (1200 VA)	
Inductive load AC15		2.5 A/230 VAC	
Mechanical life		≥ 10 x 10 <sup>6</sup> operations	
Electrical life		≥ 1 x 10 <sup>5</sup> operations, AC1	
Operating frequency		≤ 360 operations/h	
Wiring		$1 \uparrow \downarrow 1$ output for motor 1, $2 \uparrow \downarrow 2$ output for motor 2,	

## **Input Specifications**

Keypad	For local ON/OFF switchin
кеурац	FOI IOCAI ON/OFF SWILCHIN

## **Supply Specifications**

Power supply  Rated operational voltage	Overvoltage cat. II (IEC 60664-1, par. 4.3.3.2) 15 to 24 VDC ± 20%
Operational voltage range	15 to 30 VDC (ripple included)
Rated operational power	3 W
Protection for reverse polarity	Yes
Connection	2xA1 (+) and 2xA2 (-)- (2 pairs of terminals internally connected) Max 3A
Power on delay	Typ. 4 s
Power off delay	≤1s

## **Dupline® Specifications**

Voltage	8.2 V
Maximum Dupline® voltage	10 V
Minimum Dupline® voltage	5.5 V
Maximum Dupline® current	1.1 mA

The Dupline® bus is present on the internal bus: the modules can be connected one next to the other without the need of wiring the dupline bus. See "Wiring diagram".



### **General Specifications**

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Installation category	Cat. II	Connection	
Dielectric strength		Terminal	12 screw-type
Power supply to dupline	500 V impulse (1.2/50 μs)	Cable cross-section area	max. 1.5 mm <sup>2</sup>
	500 V AC for 1 min.	Tightening torque	0.4 Nm / 0.8 Nm
B !!	(IEC60664-1, TAB. F. 1)	Housing	0.000
Dupline to output,	6 KV impulse 1.2/50μμs 4 KV AC for 1 min.	Dimensions	2 DIN module
power supply to output		Material	Noryl
	(IEC60664-1, TAB. A. 1)	Weight	150 g
Address assignment	Automatic: the controller	Approvals	cRUus, according to UL60950
Address assignment	recognises the module		UL notes:
	through the SIN (Specific		Max room temperature: 40°C
	Identification Number) that		A readily accessible discon-
	has to be filled in the SH		necting device shall be added in the building installation
	tool.	OF Mandain	
Fail-safe mode	In case of interruption of the	CE Marking	Yes
	smart-house connection, the	EMC	EN 04000 0 0
	motor will stop and it will be	Immunity	EN 61000-6-2 EN 61000-4-2
	possible to control it locally	<ul><li>Electrostatic discharge</li><li>Radiated radiofrequency</li></ul>	EN 61000-4-2 EN 61000-4-3
	by means of the pushbutton	- Burst immunity	EN 61000-4-3 EN 61000-4-4
Environment		- Surge	EN 61000-4-5
Degree of protection		- Conducted radio frequency	EN 61000-4-6
Front	IP 50	- Power frequency magnetic	
Screw terminal	IP 20	fields	EN 61000-4-8
Pollution degree	2 (IEC 60664-1, par. 4.6.2)	<ul> <li>Voltage dips, variations,</li> </ul>	
Operating temperature	-20° to +50°C (-4° to 122°F)	interruptions	EN 61000-4-11
Storage temperature	-50° to +85°C (-58° to 185°F)	Emission	EN 61000-6-3
Humidity (non-condensing)	20 to 80% RH	- Conducted and radiated	01000 00 (51155000)
LED's indication	4	emissions	CISPR 22 (EN55022), cl. B
Power LED	1 green	<ul><li>Conducted emissions</li><li>Radiated emissions</li></ul>	CISPR 16-2-1 (EN55016-2-1) CISPR 16-2-3 (EN55016-2-3)
Dupline LED Motor status	1 yellow 4 red	- naulateu emissions	CISEN 10-2-3 (ENSSU10-2-3)
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## **Mode of Operation**

#### **Push button**

The push button is used for local switching ON/OFF of the output, without the need to connect the bus for test purpose.

The command from the pushbutton will only be recognized if it is kept pressed for more than 1 second: the two outputs will be activated for the whole time the push button is kept pressed. Once the push button is released, the outputs are deactivated. Every time the button is pressed, the direction of the motors is changed, always respecting the reverse delay time.

This rollerblind module is driven by the SH2WEB24 controller to move rollerblinds, sunblinds and shutters. It receives the UP and DOWN command from the SH2WEB24, and then activates the relevant output accordingly. The two outputs are driven independently and can be managed by different rollerblind functions.

The UP/DOWN output remains active for a time known as "running time" or until another UP/DOWN command is received. Before reversing the movement, the output remains

deactivated for a time called "reverse delay". The reverse delay times are sent to the SH2ROAC224 by the SH2WEB24 and can be different for each output. The running time is managed by the controller.

If the tilting function is enabled, the SH2ROAC224 will be able to manage the tilting command received from the SH2WEB24. The tilting command can be of two types: tilting UP and tilting DOWN. Once this command is received, the SH2ROAC224 will activate the UP or DOWN output for the tilting time always

respecting the reverse delay time.

#### **Addressing**

No addressing is needed since the module is provided with a specific identification number (SIN): the user has only to insert the SIN number in the SH tool when creating the system configuration.

Used channels: 2 output channels.



#### **LEDs Indication**

Red LED: 4 motor LEDs.

1? LED (red)

Motor1 DOWN: ON if motor 1 DOWN command active.

1? LED (red)

Motor1 UP: ON if motor 1 UP command active.

2? LED (red)

Motor2 DOWN: ON if motor

2 DOWN command active. 2? LED (red)

Motor2 UP: ON if motor 2 UP command active.

RED LED blinks during reverse time.

Locally, the reverse time is

Green LED: Power status.

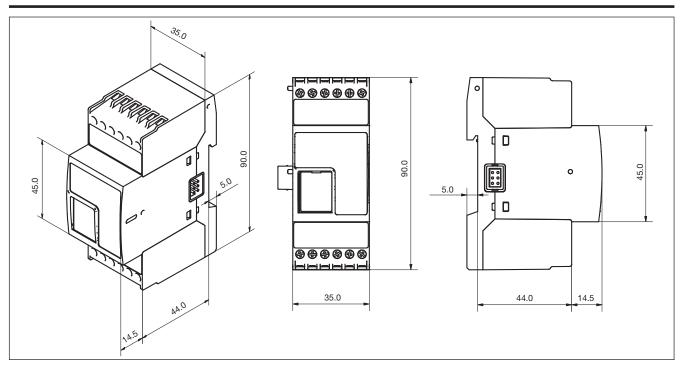
ON: supply ON OFF: supply OFF

**Yellow LED**: if the dupline bus is working properly, it is always ON.

If there is a fault on the bus it will be flashing.

It is OFF if the bus is OFF or not connected.

#### **Dimensions**



## **Wiring Diagrams**

